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# Nonautonomous Dynamical Systems

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obviously, any uniform pullback **discrete-time nonautonomous dynamical systems** - discrete-time  
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attractivity, repul-sivity, bifurcation and transition. several examples illustrate these ... **research article on  
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systems dhavalthakkar 1 andruchidas 2 vadodara institute of engineering, kotambi, vadodara , india **on  
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driven pendulum in spite of the fact that the classical pendulum is a very old **periodic solutions of second-  
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systems we will study this problem under the following assumptions: (1)  $v(t,x) \geq 0$ ,  $t \in \mathbb{R}$ ,  $x \in \mathbb{R}^n$ ; (1.5) **special  
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